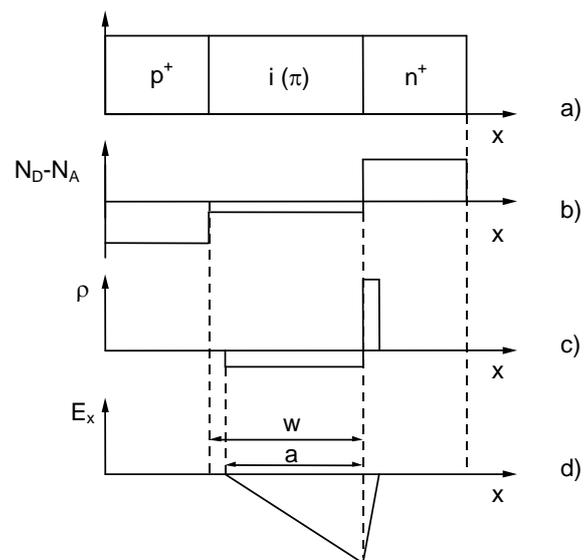
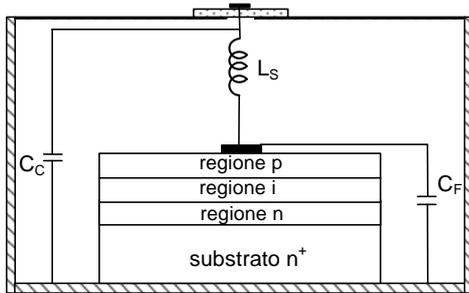


# DIODI PIN

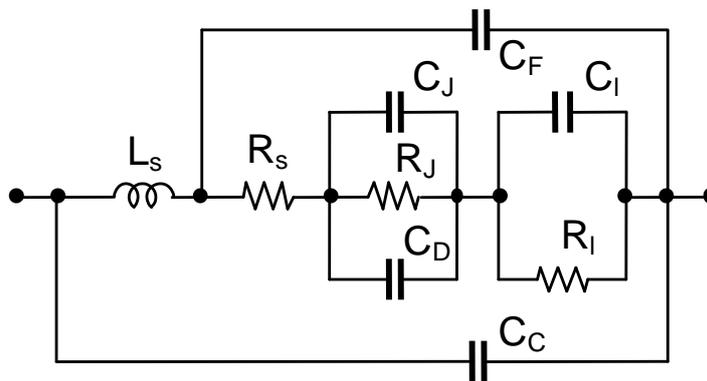
## GEOMETRIA



## CASE



## MODELLO

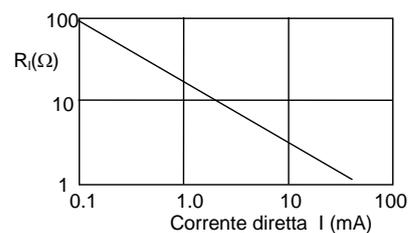
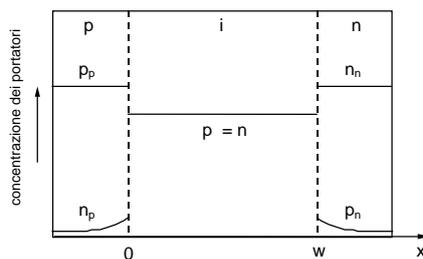


## POLARIZZAZIONE INVERSA SPINTA

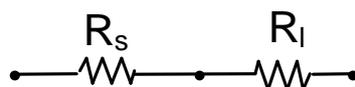


Se si considera ad esempio la frequenza di 1 GHz con  $C = C_j = 0.2$  pF si ha  $X \approx 800 \Omega$ .  
 Questa impedenza è maggiore dell'impedenza delle comuni linee di trasmissione ( $50 \Omega$ ) per cui in queste condizioni il PIN si comporta come un circuito aperto

## POLARIZZAZIONE DIRETTA



$$R_1 I = 50 \text{ mV}$$

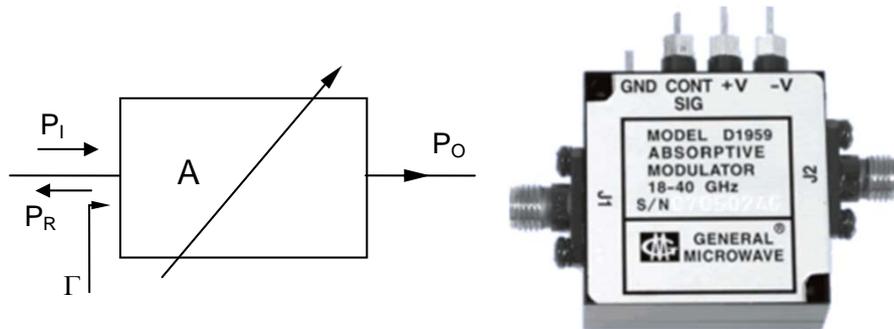


$$I = 10 \text{ mA} \rightarrow R_1 = 5 \Omega$$

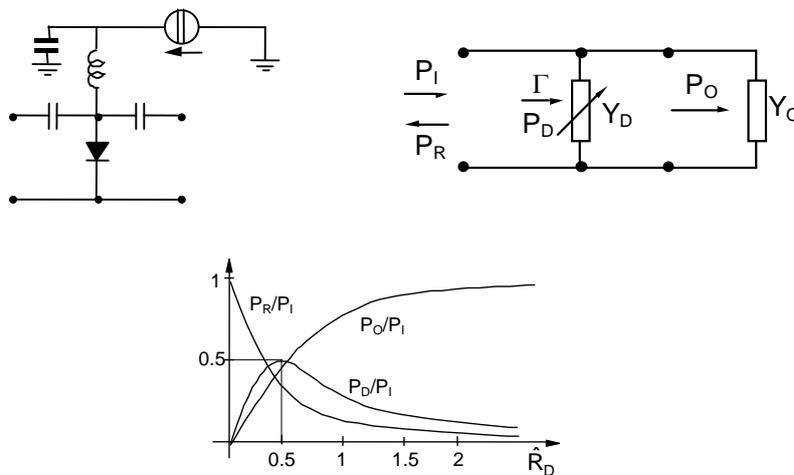
$$I = 1 \text{ mA} \rightarrow R_1 = 50 \Omega$$

$$I = 0.1 \text{ mA} \rightarrow R_1 = 500 \Omega$$

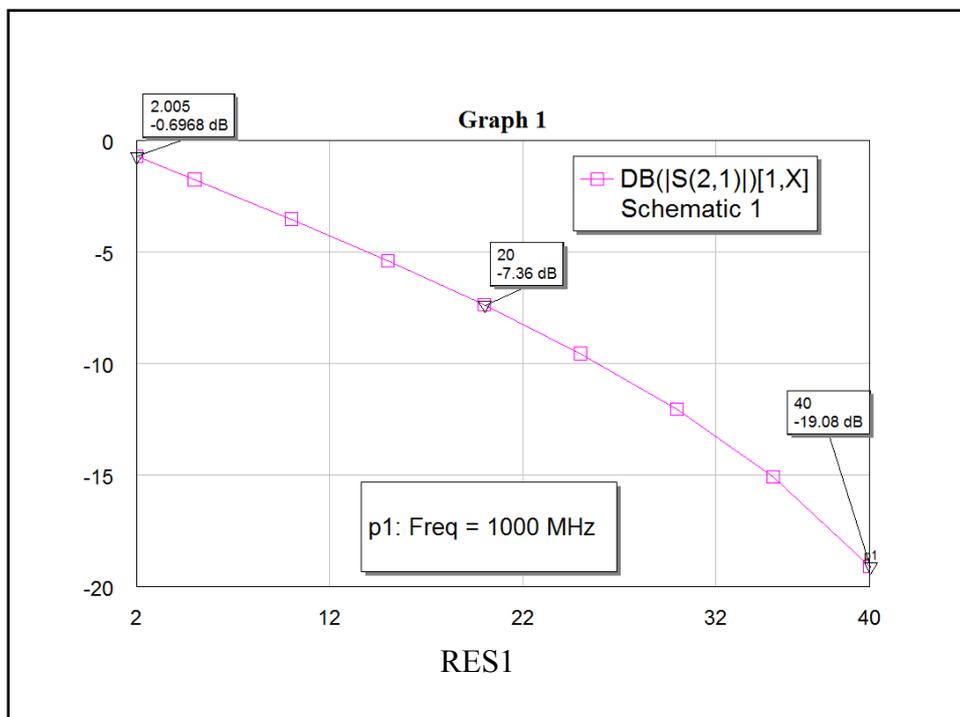
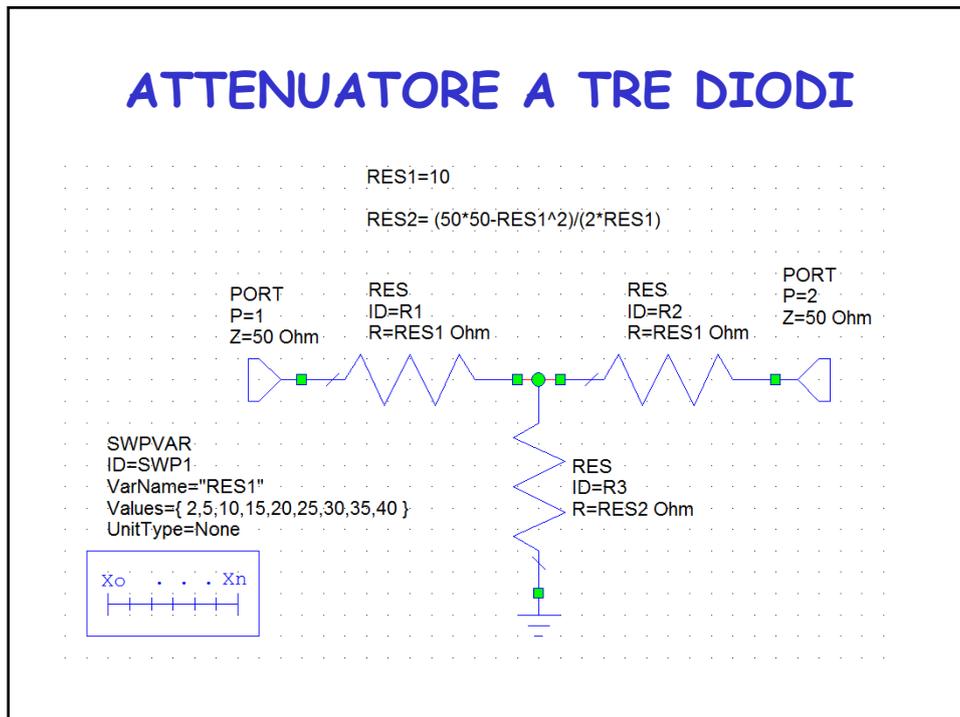
## ATTENUATORI VARIABILI



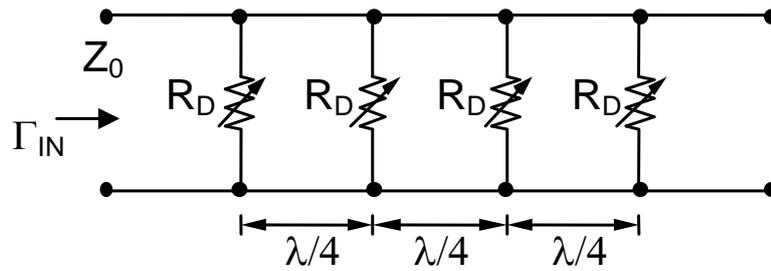
## ATTENUATORE A SINGOLO DIODO



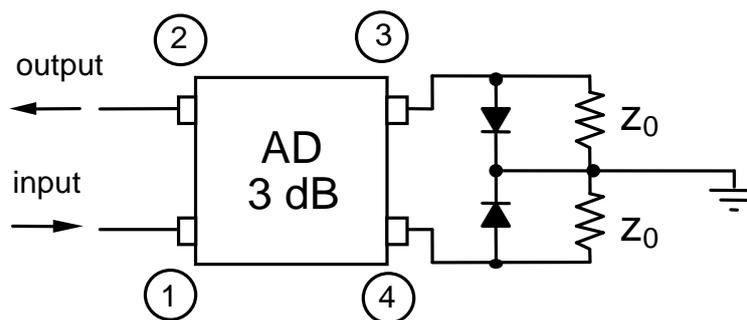
# ATTENUATORE A TRE DIODI



## ATTENUATORE A TRASFORMATORE



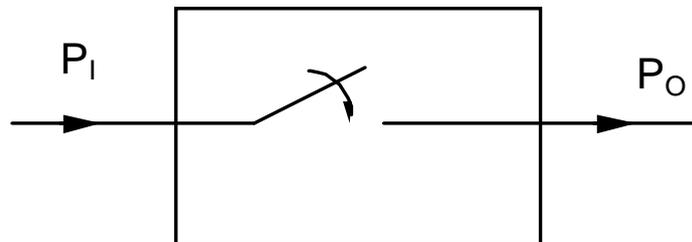
## ATTENUATORE CON AD a 90°



$$\mathbf{b}_2 = \frac{-j}{\sqrt{2}} \mathbf{a}_3 + \frac{-1}{\sqrt{2}} \mathbf{a}_4 = \frac{j}{\sqrt{2}} \Gamma_D (-\mathbf{b}_3 + j\mathbf{b}_4) = \frac{j}{\sqrt{2}} \Gamma_D \left( \frac{1}{\sqrt{2}} \mathbf{a}_1 + \frac{1}{\sqrt{2}} \mathbf{a}_1 \right) = j\Gamma_D \mathbf{a}_1$$

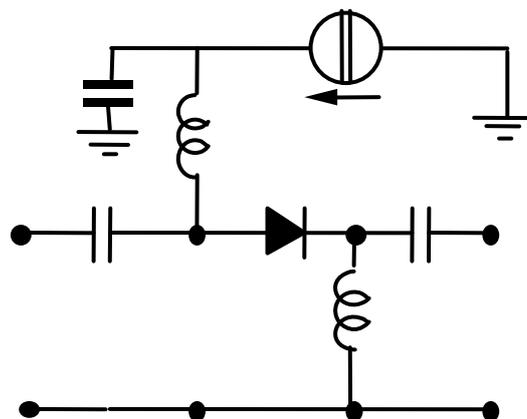
$$\mathbf{b}_1 = \frac{-1}{\sqrt{2}} \mathbf{a}_3 + \frac{-j}{\sqrt{2}} \mathbf{a}_4 = \frac{1}{\sqrt{2}} \Gamma_D (-\mathbf{b}_3 - j\mathbf{b}_4) = \frac{1}{\sqrt{2}} \Gamma_D \left( \frac{1}{\sqrt{2}} \mathbf{a}_1 - \frac{1}{\sqrt{2}} \mathbf{a}_1 \right) = 0$$

## INTERRUTTORE (SPST)

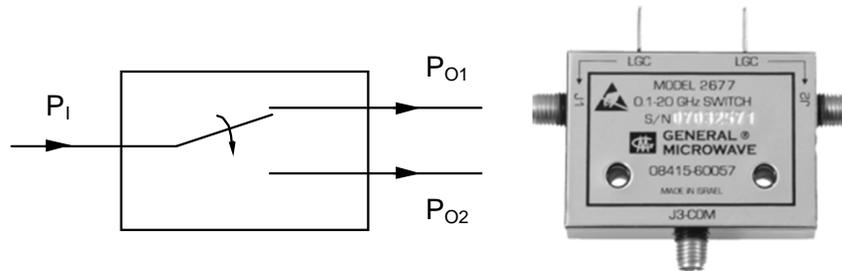


Lo schema logico di un interruttore con un ingresso ed un'uscita (Single Pole Single Throw)

## SCHEMA CIRCUITALE

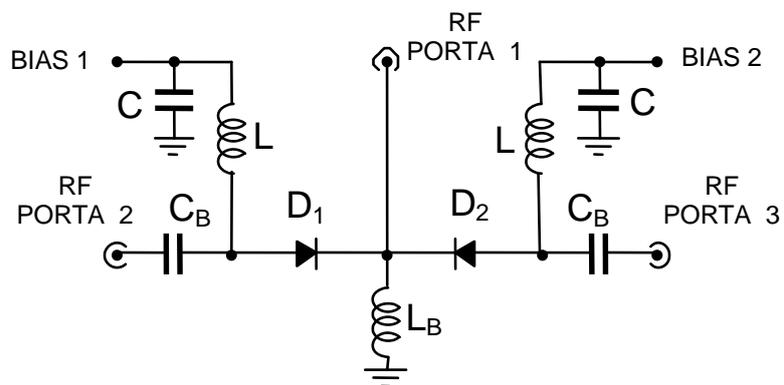


## DEVIATORE (SPDT)

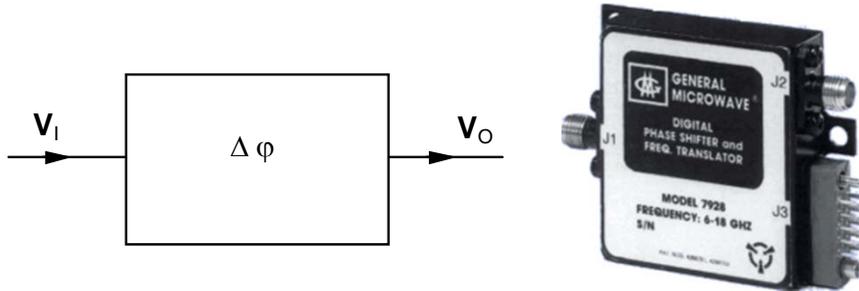


deviatore con un ingresso e due uscite (Single Pole Double Throw).

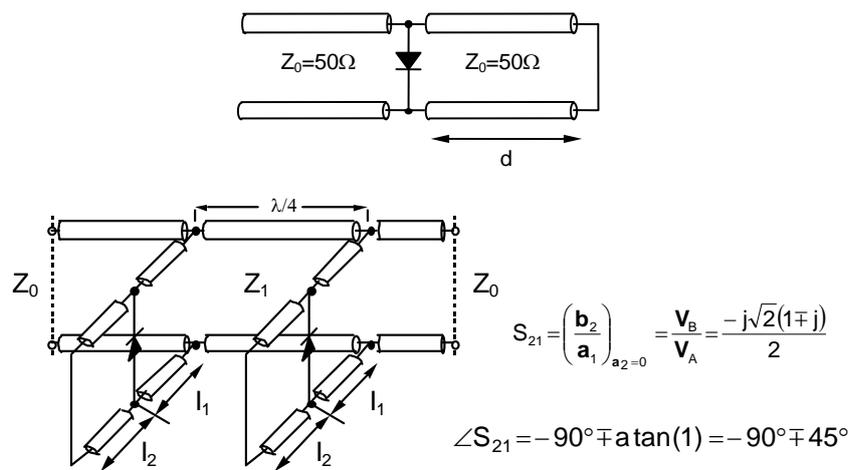
## SCHEMA CIRCUITALE



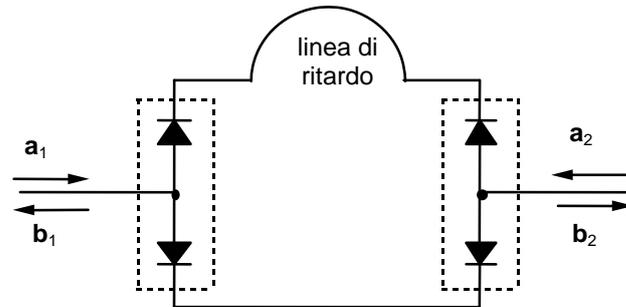
# SFASATORI



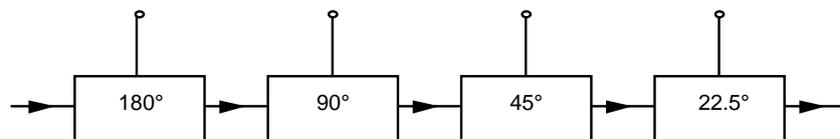
# SFASATORE A DOPPIO STUB



## SFASATORE A LINEA DI RITARDO



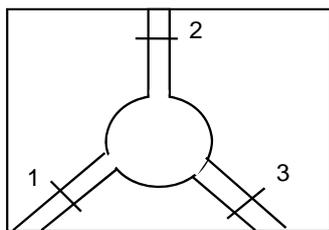
## SFASATORE A 4 bit



0, 22.5, 45, .....360

# Circolatori e Isolatori

## Circolatore a ferrite

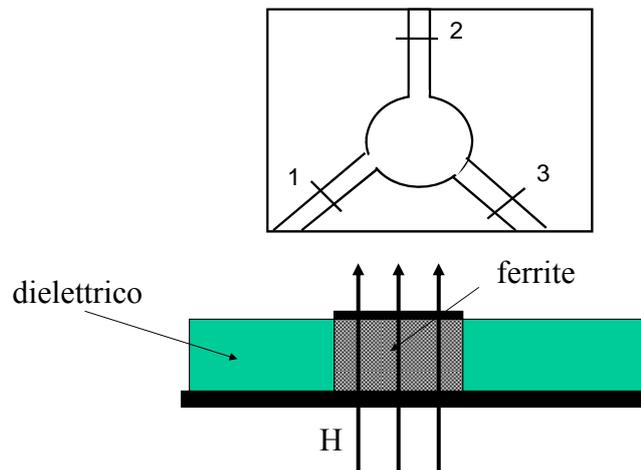


$$[S] = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

I circolatori sono spesso utilizzati nei sistemi ricetrasmittenti per separare il canale di ricezione da quello di trasmissione

operando come isolatori, possono essere collocati all'uscita degli oscillatori per evitare che la potenza riflessa dal carico interferisca con le oscillazioni

## Realizzazione su microstriscia



## Isolatori

$$[S] = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix}$$

